



# COMMON FIXED POINTS FOR FOUR MAPS IN ORDERED FUZZY METRIC SPACES USING $(\psi, \phi, \varphi)$ -CONTRACTIONS WITH ADMISSIBLE FUNCTIONS

K.P.R.Rao<sup>1</sup>, P.Ranga Swamy<sup>2</sup> and V.C.C.Raju<sup>3</sup>

<sup>1</sup>Department of Mathematics, Acharya Nagarjuna University, Nagarjuna Nagar-522 510, A.P., INDIA  
E-mail: kprao2004@yahoo.com

<sup>2</sup>Department of Mathematics, St. Ann's College of Engineering and Technology, Chirala-523 187, A.P., INDIA  
E-mail: puligeti@gmail.com

<sup>3</sup>Department of Mathematics, University of Botswana, Private Bag UB00704, Gaborone, Botswana  
E-mail: varanasi@mopipi.ub.bw

\*Corresponding author.

**Abstract** In this paper, we prove a unique common fixed point theorem for two pairs of mappings satisfying  $(\psi, \phi, \varphi)$  admissible contractive condition in partially ordered fuzzy metric spaces. Our result generalizes and improves results of Gregori and Sapena [6] and Gopal and Vetro [4]. We also give an example to support our theorem.

**MSC:** 54H25, 47H10

**Keywords:** Fuzzy metric space, compatible maps,  $\alpha$ -admissible functions, common fixed points.

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## 1. INTRODUCTION

The concept of fuzzy sets was introduced initially by Zadeh [17] in 1965. George and Veeramani [3] modified the concept of fuzzy topological spaces induced by fuzzy metric introduced by Kramosil and Michalek [8] and Grabiec [5] and proved the contraction principle in the setting of fuzzy metric spaces. Many authors, for example, [2, 5, 6, 9, 10, 12, 15, 16] have proved fixed and common fixed point theorems in fuzzy metric spaces. We denote  $\mathcal{R}$ ,  $\mathcal{R}^+$  and  $\mathcal{N}$  for the sets of real numbers, non-negative real numbers and natural numbers respectively. Now, we give the following preliminaries.

**Definition 1.1** ([14]). A binary operation  $*$  :  $[0, 1] \times [0, 1] \rightarrow [0, 1]$  is a continuous  $t$ -norm if it satisfies the following conditions:

- (1)  $*$  is associative and commutative,

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- (2)  $*$  is continuous,
- (3)  $a * 1 = a$  for all  $a \in [0, 1]$ ,
- (4)  $a * b \leq c * d$  whenever  $a \leq c$  and  $b \leq d$ , for each  $a, b, c, d \in [0, 1]$ .

Two typical examples of a continuous  $t$ -norm are  $a * b = ab$  and  $a * b = \min\{a, b\}$ .

We use the following definition due to George and Veeramani [3].

**Definition 1.2**([3]). A 3-tuple  $(X, M, *)$  is called a *fuzzy metric space* if  $X$  is an arbitrary (non-empty) set,  $*$  is a continuous  $t$ -norm and  $M$  is a fuzzy set on  $X^2 \times (0, \infty)$ , satisfying the following conditions for each  $x, y, z \in X$  and  $t, s > 0$ ,

- (1)  $M(x, y, t) > 0$ ,
- (2)  $M(x, y, t) = 1$  if and only if  $x = y$ ,
- (3)  $M(x, y, t) = M(y, x, t)$ ,
- (4)  $M(x, y, t) * M(y, z, s) \leq M(x, z, t + s)$ ,
- (5)  $M(x, y, \cdot) : (0, \infty) \rightarrow [0, 1]$  is continuous.

Let  $(X, M, *)$  be a fuzzy metric space. For  $t > 0$ , the *open ball*  $B(x, r, t)$  with center  $x \in X$  and radius  $0 < r < 1$  is defined by

$$B(x, r, t) = \{y \in X : M(x, y, t) > 1 - r\}.$$

If  $(X, M, *)$  is a fuzzy metric space, let  $\tau$  be the set of all  $A \subset X$  with  $x \in A$  if and only if there exist  $t > 0$  and  $0 < r < 1$  such that  $B(x, r, t) \subset A$ . Then  $\tau$  is a topology on  $X$  (induced by the fuzzy metric  $M$ ). This topology is Hausdorff and first countable.

A sequence  $\{x_n\}$  in  $X$  converges to  $x$  if and only if  $M(x_n, x, t) \rightarrow 1$  as  $n \rightarrow \infty$ , for each  $t > 0$ . It is called a  $G$ -Cauchy sequence in the sense of [3] if  $\lim_{n \rightarrow \infty} M(x_n, x_{n+p}, t) = 1$ , for all  $t > 0$  and each  $p \in \mathcal{N}$ . The fuzzy metric space  $(X, M, *)$  is said to be *G-complete* if every  $G$ -Cauchy sequence is convergent.

**Example 1.3.** Let  $X = \mathcal{R}$ . Put  $a * b = ab$  or  $\min\{a, b\}$  for all  $a, b \in [0, 1]$ . For all  $x, y \in X$ , define  $M(x, y, t) = \frac{t}{t + |x - y|}$  for  $t > 0$  and  $M(x, y, 0) = 0$ . Then  $(X, M, *)$  is a fuzzy metric space.

**Example 1.4.** Let  $X = \mathcal{R}$ . Put  $a * b = ab$  for all  $a, b \in [0, 1]$ . For all  $x, y \in X$ , define  $M(x, y, t) = e^{-\frac{|x - y|}{t}}$  for  $t > 0$  and  $M(x, y, 0) = 0$ . Then  $(X, M, *)$  is a fuzzy metric space.

**Lemma 1.5.**[5] Let  $(X, M, *)$  be a fuzzy metric space. Then  $M(x, y, t)$  is non-decreasing with respect to  $t$ , for all  $x, y$  in  $X$ .

**Definition 1.6.** Let  $(X, M, *)$  be a fuzzy metric space. Then  $M$  is said to be *continuous* on  $X^2 \times (0, \infty)$  if  $\lim_{n \rightarrow \infty} M(x_n, y_n, t_n) = M(x, y, t)$ , whenever a sequence  $\{(x_n, y_n, t_n)\}$  in  $X^2 \times (0, \infty)$  converges to a point  $(x, y, t) \in X^2 \times (0, \infty)$ . i.e.  $\lim_{n \rightarrow \infty} M(x_n, x, t) = \lim_{n \rightarrow \infty} M(y_n, y, t) = 1$  and  $\lim_{n \rightarrow \infty} M(x, y, t_n) = M(x, y, t)$ .

**Lemma 1.7.**([11]) Let  $(X, M, *)$  be a fuzzy metric space. Then  $M$  is a continuous function on  $X^2 \times (0, \infty)$ .

**Definition 1.8.**([10]) Let  $(X, M, *)$  be a fuzzy metric space and  $f, S : X \rightarrow X$ . The pair  $(f, S)$  is said to be compatible if  $\lim_{n \rightarrow \infty} M(fSx_n, Sfx_n, t) = 1$  for every  $t > 0$ , whenever there exists a sequence  $\{x_n\}$  in  $X$  such that  $f x_n \rightarrow z$  and  $S x_n \rightarrow z$  as  $n \rightarrow \infty$  for some  $z \in X$ .

**Definition 1.9.**([7]) Let  $X$  be a non-empty set and  $f, S : X \rightarrow X$ . The pair  $(f, S)$  is said to be weakly compatible if  $fSu = Sfu$  whenever  $fu = Su$  for  $u \in X$ .

Samet et.al ([13]) introduced the notion of  $\alpha$ -admissible mappings as follows

**Definition 1.10.** ([13]) Let  $X$  be a non empty set,  $T : X \rightarrow X$  and

$\alpha : X \times X \rightarrow \mathcal{R}^+$  be mappings. Then  $T$  is called  $\alpha$ -admissible if for all  $x, y \in X$ , we have

$\alpha(x, y) \geq 1$  implies  $\alpha(Tx, Ty) \geq 1$ .

Some interesting examples of such mappings are given in ([13]).

Gopal and Vetro [4] defined the following

**Definition 1.11.** Let  $(X, M, *)$  be a fuzzy metric space. The map  $T : X \rightarrow X$  is  $\alpha$ -admissible if there exists a function  $\alpha : X \times X \times (0, \infty) \rightarrow \mathcal{R}^+$  such that  $\alpha(x, y, t) \geq 1$  implies  $\alpha(Tx, Ty, t) \geq 1$  for all  $x, y \in X$  and for all  $t > 0$ .

**Theorem 1.12.** (Theorem 3.6, [4]) Let  $(X, M, *)$  be a  $G$ -complete fuzzy metric space. Let  $T : X \rightarrow X$  and  $\alpha : X \times X \times (0, \infty) \rightarrow \mathcal{R}^+$  be satisfying

$$(i) \alpha(x, y, t) \left( \frac{1}{M(Tx, Ty, t)} - 1 \right) \leq \phi \left( \frac{1}{M(x, y, t)} - 1 \right), \forall x, y \in X \text{ and } \forall t > 0,$$

where  $\phi : \mathcal{R}^+ \rightarrow \mathcal{R}^+$  is right continuous and  $\phi(r) < r, \forall r > 0$ ,

(ii)  $T$  is  $\alpha$ -admissible,

(iii) there exists  $x_0 \in X$  such that  $\alpha(x_0, Tx_0, t) \geq 1, \forall t > 0$ ,

(iv) if  $\{x_n\}$  is a sequence in  $X$  such that  $\alpha(x_n, x_{n+1}, t) \geq 1, \forall n \in \mathcal{N}$  and  $\forall t > 0$  and  $x_n \rightarrow x$ , then  $\alpha(x_n, x, t) \geq 1, \forall n \in \mathcal{N}$  and  $\forall t > 0$ .

Then  $T$  has a fixed point in  $X$ .

In this paper, we introduce  $\alpha$ -admissible condition for two pairs of maps in fuzzy metric spaces as follows

**Definition 1.13.** Let  $(X, M, *)$  be a fuzzy metric space and  $f, g, S, T : X \rightarrow X$  be mappings and  $\alpha : X \times X \times (0, \infty) \rightarrow \mathcal{R}^+$  be a function. We say that the pair  $(f, g)$  satisfies  $\alpha$ -admissible condition with respect to the pair  $(S, T)$  if  $\alpha(Sx, Ty, t) \geq 1$  implies  $\alpha(fx, gy, t) \geq 1$  and  $\alpha(Tx, Sy, t) \geq 1$  implies  $\alpha(gx, fy, t) \geq 1 \forall x, y \in X$  and  $\forall t > 0$ .

Recently Abbas et al. [1] introduced the new concepts in a partially ordered set as follows

**Definition 1.14.** ([1]) Let  $(X, \preceq)$  be a partially ordered set and  $f, g : X \rightarrow X$ .

(i)  $f$  is said to be a dominating map if  $x \preceq fx$ .

(ii)  $f$  is said to be a weak annihilator of  $g$  if  $fgx \preceq x$ .

Using these concepts, we now prove a unique common fixed point theorem for four maps with  $\alpha$ -admissible condition in partially ordered fuzzy metric spaces.

## 2. MAIN RESULTS

**Theorem 2.1:** Let  $(X, M, *, \preceq)$  be a partially ordered  $G$ -complete fuzzy metric space and  $f, g, S, T : X \rightarrow X$  and  $\alpha : X \times X \times (0, \infty) \rightarrow \mathcal{R}^+$  be a function satisfying

(2.1.1)  $f$  and  $g$  are dominating maps and  $f$  and  $g$  are weak annihilators of  $T$  and  $S$  respectively,

(2.1.2)  $f(X) \subseteq T(X), g(X) \subseteq S(X)$ ,

$$(2.1.3) \alpha(Sx, Ty, t) \psi \left( \frac{1}{M(fx, gy, t)} - 1 \right) \leq \phi \left( \frac{1}{m(x, y, t)} - 1 \right) - \varphi \left( \frac{1}{m(x, y, t)} - 1 \right)$$

for all comparable elements  $x, y \in X, \forall t > 0$ , where

$m(x, y, t) = \min\{M(Sx, Ty, t), M(fx, Sx, t), M(gy, Ty, t)\}$  and

$\psi, \phi, \varphi : \mathcal{R}^+ \rightarrow \mathcal{R}^+$  are such that  $\psi$  is monotonically increasing and continuous and  $\phi$  and  $\varphi$  are upper and lower semi continuous respectively with satisfying the following condition

$$(A) : \psi(t) - \phi(t) + \varphi(t) > 0 \text{ for all } t > 0$$

(2.1.4)  $(f, g)$  is  $\alpha$ -admissible w.r.to  $(S, T)$ ,

(2.1.5)  $\alpha(Sx_1, fx_1, t) \geq 1$  and  $\alpha(fx_1, Sx_1, t) \geq 1$  for some  $x_1 \in X$  and  $\forall t > 0$ ,

(2.1.6)(a)  $S$  is continuous, the pair  $(f, S)$  is compatible and the pair  $(g, T)$  is weakly compatible and we assume  $\alpha(Sy_{2n}, y_{2n-1}, t) \geq 1, \alpha(z, y_{2n-1}, t) \geq 1, \alpha(y_{2n}, Tz, t) \geq 1$  and  $\alpha(z, z, t) \geq 1 \forall n \in \mathcal{N}$  and  $\forall t > 0$  whenever there exists  $\{y_n\}$  in  $X$  such that  $\alpha(y_n, y_{n+1}, t) \geq 1$  and  $\alpha(y_{n+1}, y_n, t) \geq 1 \forall n \in \mathcal{N}$  and for all  $t > 0$  and  $y_n \rightarrow z$  for some  $z \in X$ .

(or)

(2.1.6)(b)  $T$  is continuous, the pair  $(g, T)$  is compatible and the pair  $(f, S)$  is weakly compatible and we assume  $\alpha(y_{2n}, Ty_{2n-1}, t) \geq 1, \alpha(y_{2n}, z, t) \geq 1, \alpha(Sz, y_{2n-1}, t) \geq 1$  and  $\alpha(z, z, t) \geq 1 \forall n \in \mathcal{N}$  and  $\forall t > 0$  whenever there exists  $\{y_n\}$  in  $X$  such that  $\alpha(y_n, y_{n+1}, t) \geq 1$  and  $\alpha(y_{n+1}, y_n, t) \geq 1 \forall n \in \mathcal{N}$  and for all  $t > 0$  and  $y_n \rightarrow z$  for some  $z \in X$ .

(2.1.7) if for a non-decreasing sequence  $\{x_n\}$  in  $X$  with  $x_n \preceq y_n, \forall n \in \mathcal{N}$  and  $y_n \rightarrow z$  implies  $x_n \preceq z, \forall n \in \mathcal{N}$ .

Then  $f, g, S$  and  $T$  have a common fixed point in  $X$ .

(2.1.8) Further if we assume that  $\alpha(u, v, t) \geq 1 \forall t > 0$  whenever  $u$  and  $v$  are common fixed points of  $f, g, S$  and  $T$  and the set of common fixed points of  $f, g, S$  and  $T$  is well ordered then  $f, g, S$  and  $T$  have unique common fixed point in  $X$ .

**Proof.** From (2.1.5), there exists  $x_1 \in X$  such that  $\alpha(Sx_1, fx_1, t) \geq 1$  and  $\alpha(fx_1, Sx_1, t) \geq 1, \forall t > 0$ .

From (2.1.2), we define the sequences  $\{x_n\}$  and  $\{y_n\}$  as

$$y_{2n+1} = fx_{2n+1} = Tx_{2n+2}, y_{2n+2} = gx_{2n+2} = Sx_{2n+3}, n = 0, 1, 2, \dots$$

Now

$$\begin{aligned} \alpha(Sx_1, fx_1, t) \geq 1 &\Rightarrow \alpha(Sx_1, Tx_2, t) \geq 1 \text{ from definition of } \{y_n\} \\ &\Rightarrow \alpha(fx_1, gx_2, t) \geq 1, \text{ from (2.1.4), i.e } \alpha(y_1, y_2, t) \geq 1 \\ &\Rightarrow \alpha(Tx_2, Sx_3, t) \geq 1 \text{ from definition of } \{y_n\} \\ &\Rightarrow \alpha(gx_2, fx_3, t) \geq 1, \text{ from (2.1.4), i.e } \alpha(y_2, y_3, t) \geq 1. \end{aligned}$$

Continuing in this way, we have

$$\alpha(y_n, y_{n+1}, t) \geq 1, \forall n \in \mathcal{N} \text{ and } \forall t > 0 \tag{2.1}$$

Similarly by using  $\alpha(fx_1, Sx_1, t) \geq 1$ , we can show that

$$\alpha(y_{n+1}, y_n, t) \geq 1, \forall n \in \mathcal{N} \text{ and } \forall t > 0 \tag{2.2}$$

From (2.1.1), we have

$$\begin{aligned} x_{2n+1} &\preceq fx_{2n+1} = Tx_{2n+2} \preceq fTx_{2n+2} \preceq x_{2n+2}, \\ x_{2n+2} &\preceq gx_{2n+2} = Sx_{2n+3} \preceq gSx_{2n+3} \preceq x_{2n+3}. \end{aligned} \text{ Thus}$$

$$x_n \preceq x_{n+1}, \forall n \in \mathcal{N} \tag{2.3}$$

**Case (i):** Suppose  $y_{2m} = y_{2m+1}$  for some  $m$ .

Assume that  $y_{2m+1} \neq y_{2m+2}$ .

Then there exists  $t_0 > 0$  such that  $0 < M(y_{2m+1}, y_{2m+2}, t_0) < 1$ .

From (1),  $\alpha(Sx_{2m+1}, Tx_{2m+2}, t_0) = \alpha(y_{2m}, y_{2m+1}, t_0) \geq 1$ .

Now from (3) and (2.1.3), we have

$$\begin{aligned} \psi \left( \frac{1}{M(y_{2m+1}, y_{2m+2}, t_0)} - 1 \right) &= \psi \left( \frac{1}{M(fx_{2m+1}, gx_{2m+2}, t_0)} - 1 \right) \\ &\leq \alpha(Sx_{2m+1}, Tx_{2m+2}, t_0) \psi \left( \frac{1}{M(fx_{2m+1}, gx_{2m+2}, t_0)} - 1 \right) \\ &\leq \phi \left( \frac{1}{m(x_{2m+1}, x_{2m+2}, t_0)} - 1 \right) - \varphi \left( \frac{1}{m(x_{2m+1}, x_{2m+2}, t_0)} - 1 \right) \end{aligned}$$

where

$$\begin{aligned} m(x_{2m+1}, x_{2m+2}, t_0) &= \min \{M(y_{2m+1}, y_{2m}, t_0), M(y_{2m+1}, y_{2m}, t_0), M(y_{2m+2}, y_{2m+1}, t_0)\} \\ &= M(y_{2m+1}, y_{2m+2}, t_0). \end{aligned}$$

Thus

$$\psi \left( \frac{1}{M(y_{2m+1}, y_{2m+2}, t_0)} - 1 \right) \leq \phi \left( \frac{1}{M(y_{2m+1}, y_{2m+2}, t_0)} - 1 \right) - \varphi \left( \frac{1}{M(y_{2m+1}, y_{2m+2}, t_0)} - 1 \right).$$

It is a contradiction to (A). Hence  $y_{2m+1} = y_{2m+2}$ .

Continuing in this way, we get  $y_{2m} = y_{2m+1} = y_{2m+2} = \dots$

Hence  $\{y_n\}$  is a Cauchy sequence in  $X$ .

**Case (ii):** Assume that  $y_n \neq y_{n+1}, \forall n$ .

As in Case (i), we have

$$\psi \left( \frac{1}{M(y_{2n+1}, y_{2n+2}, t)} - 1 \right) \leq \phi \left( \frac{1}{m(x_{2n+1}, x_{2n+2}, t)} - 1 \right) - \varphi \left( \frac{1}{m(x_{2n+1}, x_{2n+1}, t)} - 1 \right)$$

where

$$m(x_{2n+1}, x_{2n+2}, t) = \min \{M(y_{2n}, y_{2n+1}, t), M(y_{2n+1}, y_{2n+2}, t)\}.$$

If  $m(x_{2n+1}, x_{2n+2}, t) = M(y_{2n+1}, y_{2n+2}, t)$  then

$$\psi \left( \frac{1}{M(y_{2n+1}, y_{2n+2}, t)} - 1 \right) \leq \phi \left( \frac{1}{M(y_{2n+1}, y_{2n+2}, t)} - 1 \right) - \varphi \left( \frac{1}{M(y_{2n+1}, y_{2n+2}, t)} - 1 \right).$$

It is a contradiction to (A). Hence

$$\begin{aligned} \psi \left( \frac{1}{M(y_{2n+1}, y_{2n+2}, t)} - 1 \right) &\leq \phi \left( \frac{1}{M(y_{2n}, y_{2n+1}, t)} - 1 \right) - \varphi \left( \frac{1}{M(y_{2n}, y_{2n+1}, t)} - 1 \right) \\ &< \psi \left( \frac{1}{M(y_{2n}, y_{2n+1}, t)} - 1 \right), \text{ from (A)}. \end{aligned} \tag{2.4}$$

Since  $\psi$  is monotonically increasing we have

$$M(y_{2n+1}, y_{2n+2}, t) \geq M(y_{2n}, y_{2n+1}, t), \forall t > 0.$$

Similarly by using (2) and proceeding as above we can show that

$$M(y_{2n+2}, y_{2n+3}, t) \geq M(y_{2n+1}, y_{2n+2}, t), \forall t > 0.$$

Thus  $M(y_n, y_{n+1}, t) \geq M(y_{n-1}, y_n, t)$  for  $n = 2, 3, \dots$  and  $\forall t > 0$ .

Thus  $\{M(y_n, y_{n+1}, t)\}$  is an increasing sequence of positive real numbers in  $[0, 1]$  and hence converges to some  $r(t), \forall t > 0$ .

Thus  $\lim_{n \rightarrow \infty} M(y_n, y_{n+1}, t) = r(t), \forall t > 0$ .

Suppose there exists some  $t_0 > 0$  such that  $r(t_0) < 1$ .

Letting  $n \rightarrow \infty$  in (2.4) and using continuity, upper semi continuity and lower semi continuity of  $\psi, \phi$  and  $\varphi$  respectively, we get

$$\psi \left( \frac{1}{r(t_0)} - 1 \right) \leq \phi \left( \frac{1}{r(t_0)} - 1 \right) - \varphi \left( \frac{1}{r(t_0)} - 1 \right).$$

It is a contradiction from (A).

Hence  $r(t) = 1, \forall t > 0$ .

Thus

$$\lim_{n \rightarrow \infty} M(y_n, y_{n+1}, t) = 1, \forall t > 0. \tag{2.5}$$

Now for each positive integer  $p$ , we have

$$M(y_n, y_{n+p}, t) \geq M\left(y_n, y_{n+1}, \frac{t}{p}\right) * M\left(y_{n+1}, y_{n+2}, \frac{t}{p}\right) * \cdots * M\left(y_{n+p-1}, y_{n+p}, \frac{t}{p}\right).$$

letting  $n \rightarrow \infty$  and using (5), we get

$$\lim_{n \rightarrow \infty} M(y_n, y_{n+p}, t) = 1, \forall t > 0.$$

Hence  $\{y_n\}$  is a  $G$ -Cauchy sequence in  $X$ .

Since  $X$  is  $G$ -complete, there exists  $z \in X$  such that  $\{y_n\}$  converges to  $z$ . Thus  $\lim_{n \rightarrow \infty} M(y_n, z, t) = 1, \forall t > 0$ . Hence

$$\lim_{n \rightarrow \infty} f x_{2n+1} = \lim_{n \rightarrow \infty} g x_{2n+2} = \lim_{n \rightarrow \infty} T x_{2n+2} = \lim_{n \rightarrow \infty} S x_{2n+1} = z.$$

Suppose (2.1.6)(a) holds.

Since  $S$  is continuous, we have  $S^2 x_{2n+1} \rightarrow Sz$  and  $S f x_{2n+1} \rightarrow Sz$ .

Since the pair  $(f, S)$  is compatible, we have

$$\lim_{n \rightarrow \infty} M(f S x_{2n+1}, S f x_{2n+1}, t) = 1, \forall t > 0.$$

Hence  $f S x_{2n+1} \rightarrow Sz$ .

Now from (2.1.6)(a), we have

$$\alpha(SSx_{2n+1}, Tx_{2n}, t) = \alpha(Sy_{2n}, y_{2n-1}, t) \geq 1.$$

From (2.1.1), we have  $x_{2n} \preceq g x_{2n} = S x_{2n+1}$ .

By using (2.1.3), we have

$$\begin{aligned} \psi\left(\frac{1}{M(f S x_{2n+1}, g x_{2n}, t)} - 1\right) &\leq \alpha(SSx_{2n+1}, Tx_{2n}, t) \psi\left(\frac{1}{M(f S x_{2n+1}, g x_{2n}, t)} - 1\right) \\ &\leq \phi\left(\frac{1}{m(Sx_{2n+1}, x_{2n}, t)} - 1\right) - \varphi\left(\frac{1}{m(Sx_{2n+1}, x_{2n}, t)} - 1\right) \end{aligned} \quad (2.6)$$

where

$$\begin{aligned} m(Sx_{2n+1}, x_{2n}, t) &= \min\{M(SS_{2n+1}, Tx_{2n}, t), M(SS_{2n+1}, f S x_{2n+1}, t), M(Tx_{2n}, g x_{2n}, t)\} \\ &\rightarrow M(Sz, z, t) \text{ as } n \rightarrow \infty. \end{aligned}$$

Letting  $n \rightarrow \infty$  in (6), we get

$$\psi\left(\frac{1}{M(Sz, z, t)} - 1\right) \leq \phi\left(\frac{1}{M(Sz, z, t)} - 1\right) - \varphi\left(\frac{1}{M(Sz, z, t)} - 1\right)$$

which in turn yields from (A) that  $Sz = z$ .

Since  $x_{2n} \preceq g x_{2n}$  and  $g x_{2n} \rightarrow z$ , by (2.1.7), we have  $x_{2n} \preceq z$ .

From (2.1.6)(a), we have  $\alpha(Sz, Tx_{2n}, t) = \alpha(z, y_{2n-1}, t) \geq 1$ .

By using (2.1.3), we have

$$\begin{aligned} \psi\left(\frac{1}{M(f z, g x_{2n}, t)} - 1\right) &\leq \alpha(Sz, Tx_{2n}, t) \psi\left(\frac{1}{M(f z, g x_{2n}, t)} - 1\right) \\ &\leq \phi\left(\frac{1}{m(z, x_{2n}, t)} - 1\right) - \varphi\left(\frac{1}{m(z, x_{2n}, t)} - 1\right) \end{aligned} \quad (2.7)$$

where

$$\begin{aligned} m(z, x_{2n}, t) &= \min\{M(Sz, Tx_{2n}, t), M(Sz, f z, t), M(Tx_{2n}, g x_{2n}, t)\} \\ &\rightarrow M(z, f z, t) \text{ as } n \rightarrow \infty. \end{aligned}$$

Letting  $n \rightarrow \infty$  in (7), we get

$$\psi \left( \frac{1}{M(fz, z, t)} - 1 \right) \leq \phi \left( \frac{1}{M(fz, z, t)} - 1 \right) - \varphi \left( \frac{1}{M(fz, z, t)} - 1 \right)$$

which in turn yields from (A) that  $fz = z$ .

Since  $f(X) \subseteq T(X)$ , there exists  $w \in X$  such that  $z = fz = Tw$ . Also we have  $z = fz = Tw \preceq fTw \preceq w$ .

From (2.1.6)(a),  $\alpha(Sz, Tw, t) = \alpha(z, z, t) \geq 1$ .

By using (2.1.3), we have

$$\begin{aligned} \psi \left( \frac{1}{M(Tw, gw, t)} - 1 \right) &= \psi \left( \frac{1}{M(fz, gw, t)} - 1 \right) \\ &\leq \alpha(Sz, Tw, t) \psi \left( \frac{1}{M(fz, gw, t)} - 1 \right) \\ &\leq \phi \left( \frac{1}{m(z, w, t)} - 1 \right) - \varphi \left( \frac{1}{m(z, w, t)} - 1 \right) \end{aligned} \quad (2.8)$$

where

$$\begin{aligned} m(z, w, t) &= \min\{M(Sz, Tw, t), M(fz, Sz, t), M(gw, Tw, t)\} \\ &\rightarrow M(gw, Tw, t). \end{aligned}$$

Thus

$$\psi \left( \frac{1}{M(Tw, gw, t)} - 1 \right) \leq \phi \left( \frac{1}{M(Tw, gw, t)} - 1 \right) - \varphi \left( \frac{1}{M(Tw, gw, t)} - 1 \right)$$

which in turn yields from (A) that  $gw = Tw = z$ .

Since the pair  $(g, T)$  is weakly compatible, we have  $gz = gTw = Tgw = Tz$ .

Since  $x_{2n+1} \preceq fx_{2n+1}$  and  $fx_{2n+1} \rightarrow z$ , by (2.1.7), we have  $x_{2n+1} \preceq z$ .

From (2.1.6)(a),  $\alpha(Sx_{2n+1}, Tz, t) = \alpha(y_{2n}, Tz, t) \geq 1$ .

From (2.1.3), we have

$$\begin{aligned} \psi \left( \frac{1}{M(fx_{2n+1}, gz, t)} - 1 \right) &\leq \alpha(Sx_{2n+1}, Tz, t) \psi \left( \frac{1}{M(fx_{2n+1}, gz, t)} - 1 \right) \\ &\leq \phi \left( \frac{1}{m(x_{2n+1}, z, t)} - 1 \right) - \varphi \left( \frac{1}{m(x_{2n+1}, z, t)} - 1 \right) \end{aligned} \quad (2.9)$$

where

$$\begin{aligned} m(x_{2n+1}, z, t) &= \min\{M(y_{2n}, Tz, t), M(y_{2n+1}, y_{2n}, t), M(gz, Tz, t)\} \\ &\rightarrow M(z, gz, t) \text{ as } n \rightarrow \infty. \end{aligned}$$

Letting  $n \rightarrow \infty$  in (9), we get

$$\psi \left( \frac{1}{M(z, gz, t)} - 1 \right) \leq \phi \left( \frac{1}{M(z, gz, t)} - 1 \right) - \varphi \left( \frac{1}{M(z, gz, t)} - 1 \right)$$

which in turn yields from (A) that  $gz = z$ . Hence  $Tz = z$ .

Thus  $z$  is a common fixed point of  $f, g, S$  and  $T$ .

Uniqueness of common fixed point follows easily by (2.1.8).

Similarly we can prove the theorem when (2.1.6)(b) holds.

Now we give an example to illustrate Theorem 2.1

**Example 2.2.** Let  $X = [0, \infty)$  and define  $x \preceq y$  if  $y \leq x$ . Put  $a * b = \min\{a, b\}$  for all  $a, b \in [0, 1]$ . For all  $x, y \in X$  define  $M(x, y, t) = \frac{t}{t + |x - y|}$  for  $t > 0$  and  $M(x, y, 0) = 0$ . Define  $f, g, S, T : X \rightarrow X$  by  $fx = \frac{x}{2}, gx = \frac{x}{4}, Sx = 8x$  and  $Tx = 4x$  for all  $x \in X$ .

Let  $\psi, \phi, \varphi : \mathcal{R}^+ \rightarrow \mathcal{R}^+$  be defined as  $\psi(t) = t, \phi(t) = \frac{3t}{4}$  and  $\varphi(t) = \frac{t}{4}$ .

Define  $\alpha(x, y, t) = \begin{cases} 1, & \text{if } x, y \in [0, 1], \\ 0, & \text{otherwise} \end{cases}$  for all  $t > 0$ .

We have  $fx = \frac{x}{2} \leq x \Rightarrow x \preceq fx$  and  $gx = \frac{x}{4} \leq x \Rightarrow x \preceq gx$ .

Also  $fTx = 2x \geq x \Rightarrow fTx \preceq x$  and  $gSx = 2x \geq x \Rightarrow gSx \preceq x$ .

If  $x > \frac{1}{8}$  and  $y \in X$  then  $\alpha(Sx, Ty) = 0$ .

If  $x \leq \frac{1}{8}$  and  $y > \frac{1}{4}$  then  $\alpha(Sx, Ty) = 0$ .

In these cases, the condition (2.1.3) is clearly satisfied.

Suppose  $x \leq \frac{1}{8}$  and  $y \in [0, \frac{1}{4}]$  then  $\alpha(Sx, Ty) = 1$ .

We have  $\frac{1}{M(fx, gy, t)} - 1 = \frac{|2x-y|}{4t}$  and  $\frac{1}{M(Sx, Ty, t)} - 1 = \frac{4|2x-y|}{t}$ .

Clearly  $\frac{1}{m(x, y, t)} - 1 \geq \frac{1}{M(Sx, Ty, t)} - 1$  for all  $x, y \in X$  and for all  $t > 0$ .

Now,

$$\begin{aligned} \phi\left(\frac{1}{m(x, y, t)} - 1\right) - \varphi\left(\frac{1}{m(x, y, t)} - 1\right) &= \frac{1}{2}\left(\frac{1}{m(x, y, t)} - 1\right) \\ &\geq \frac{1}{2}\left(\frac{1}{M(Sx, Ty, t)} - 1\right) \\ &= \frac{2|2x-y|}{t} \\ &= 8\left(\frac{1}{M(fx, gy, t)} - 1\right) \\ &> \psi\left(\frac{1}{M(fx, gy, t)} - 1\right) \\ &= \alpha(Sx, Ty, t)\psi\left(\frac{1}{M(fx, gy, t)} - 1\right) \end{aligned}$$

Thus (2.1.3) is satisfied.

One can easily verify all the other conditions of Theorem 2.1. Clearly 0 is the unique common fixed point of  $f, g, S$  and  $T$ .

By suitably taking  $\alpha, \psi, \phi$  and  $\varphi$  in Theorem 2.1, one can obtain some previous results in fuzzy metric spaces.

### Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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Website: <http://tacs.kmutt.ac.th/>  
Email: [tacs@kmutt.ac.th](mailto:tacs@kmutt.ac.th)